

1 Recall

Recall that the primal problem (P) that we discussed yesterday:

$$P := \inf_{x \in K} f(x) \quad \text{subject to} \quad K := \begin{cases} g_i(x) \leq 0, & i = 1, \dots, m \\ h_j(x) = 0, & j = 1, \dots, \ell \end{cases} \quad (P)$$

where $f, g_i : \mathbb{R}^n \rightarrow \mathbb{R}$ are convex differentiable functions while $h_j : \mathbb{R}^n \rightarrow \mathbb{R}$ are affine functions, i.e. $h_j(x) = A_j^T x + b_j$.

and we define the **Lagrangian function** L by

$$L(x, \lambda, \mu) := f(x) + \sum_{i=1}^{\ell} \lambda_i g_i(x) + \sum_{j=1}^m \mu_j h_j(x)$$

for $\lambda_i \geq 0, \mu_j \in \mathbb{R}$ for all $i = 1, \dots, \ell$ and $j = 1, \dots, m$, and the **Lagrange dual problem** is defined as:

$$D := \sup_{\substack{\lambda_i \in \mathbb{R}_+, i=1, \dots, \ell \\ \mu_j \in \mathbb{R}, j=1, \dots, m}} d(\lambda, \mu) \quad (D)$$

where $d(\lambda, \mu) := \inf_{x \in \mathbb{R}^n} L(x, \lambda, \mu)$.

Theorem 1. Under Slater condition (i.e. there exists $x \in K$ such that $g_i(x) < 0, i = 1, \dots, m$ and $h_j(x) = 0, j = 1, \dots, \ell$), one has

1. $P = D$.
2. there exists $(\lambda^*, \mu^*) \in \mathbb{R}_+^m \times \mathbb{R}^\ell$ such that $P = D = d(\lambda^*, \mu^*)$.

Also, we discussed two systems of constraints as

$$f(x) < C, \quad \begin{cases} g_i(x) \leq 0, & i = 1, \dots, m \\ h_j(x) = 0, & j = 1, \dots, \ell \end{cases} \quad (I)$$

$$d(\lambda, \mu) \geq C, \quad \text{for } (\lambda, \mu) \in \mathbb{R}_+^m \times \mathbb{R}^\ell \quad (II)$$

and a proposition:

Proposition 2. If (I) is insolvable and Slater condition holds, then (II) is solvable.

Proof of Theorem. 1. Weak Duality: $P \geq D$.

2. Set $C = P$ in both (I) and (II) so that (I) is insolvable.

By the proposition, (II) is solvable, so there exists $(\lambda^*, \mu^*) \in \mathbb{R}_+^m \times \mathbb{R}^\ell$ such that $D \geq d(\lambda^*, \mu^*) \geq C = P$.

Thus, we have $P = d(\lambda^*, \mu^*) = D$.

□

Theorem 3. (Saddle Point)

(i) Let $(x^*, (\lambda^*, \mu^*)) \in \mathbb{R}^n \times \mathbb{R}_+^m \times \mathbb{R}^\ell$ be a saddle point in the sense that

$$L(x, \lambda^*, \mu^*) \geq L(x^*, \lambda^*, \mu^*) \geq L(x^*, \lambda, \mu), \quad \forall x \in \mathbb{R}^n, (\lambda, \mu) \in \mathbb{R}_+^m \times \mathbb{R}^\ell.$$

Then x^* is an optimizer of (P) .

(ii) Let x^* be an optimizer of (P) and Slater condition holds. Then there exists $(\lambda^*, \mu^*) \in \mathbb{R}_+^m \times \mathbb{R}^\ell$ such that $(x^*, (\lambda^*, \mu^*))$ is a saddle point of

$$L(x, \lambda^*, \mu^*) \geq L(x^*, \lambda^*, \mu^*) \geq L(x^*, \lambda, \mu), \quad \forall x \in \mathbb{R}^n, (\lambda, \mu) \in \mathbb{R}_+^m \times \mathbb{R}^\ell.$$

Proof of (ii). By Duality Theorem, there exists $(\lambda^*, \mu^*) \in \mathbb{R}_+^m \times \mathbb{R}^\ell$ such that

$$P = D = d(\lambda^*, \mu^*) = \inf_{x \in \mathbb{R}^n} L(x, \lambda^*, \mu^*)$$

This implies that

$$\begin{aligned} f(x^*) &= P = \inf_{x \in \mathbb{R}^n} L(x, \lambda^*, \mu^*) \\ &\leq L(x^*, \lambda^*, \mu^*) \\ &= f(x^*) + \sum_{i=1}^m \lambda_i^* g_i(x^*) + \sum_{j=1}^{\ell} \mu_j^* h_j(x^*) \end{aligned}$$

Since $x^* \in K$, we know

$$\begin{cases} g_i(x) \leq 0, & i = 1, \dots, m \\ h_j(x^*) = 0, & j = 1, \dots, \ell \end{cases} \implies \sum_{i=1}^m \lambda_i^* g_i(x^*) \leq 0 \quad \text{and} \quad \sum_{j=1}^{\ell} \mu_j^* h_j(x^*) = 0.$$

From the above, we can deduce that

$$\begin{aligned} f(x^*) &\leq f(x^*) + \underbrace{\sum_{i=1}^m \lambda_i^* g_i(x^*)}_{\leq 0} \implies \sum_{i=1}^m \lambda_i^* g_i(x^*) = 0 \\ &\implies \lambda_i^* g_i(x^*) = 0, \quad \forall i = 1, \dots, m \end{aligned}$$

Hence, we have

$$\begin{aligned} L(x, \lambda^*, \mu^*) &\geq L(x^*, \lambda^*, \mu^*), \quad \forall x \in \mathbb{R}^n \\ &= f(x^*) \\ &\geq f(x^*) + \underbrace{\sum \lambda_i g_i(x^*)}_{\leq 0} + \underbrace{\sum \mu_j h_j(x^*)}_{=0} \\ &= L(x^*, \lambda, \mu) \end{aligned}$$

for any $(\lambda, \mu) \in \mathbb{R}_+^m \times \mathbb{R}^\ell$. □

2 Qualification

Recall that, we discuss the **Mangasarian Fromovitz** qualification condition before.

Proposition 4. *Let $x \in K$ satisfies the followings (**Mangasarian Fromovitz condition**)*

1. *the family of vectors $(\nabla h_1(x), \dots, \nabla h_m(x))$ is linearly independent.*
2. *there exists a vector $v \in \mathbb{R}^n$ satisfying*

$$\langle \nabla h_j(x), v \rangle = 0, \quad \forall j = 1, \dots, m$$

and

$$\langle \nabla g_i(x), v \rangle < 0, \quad \forall i \in I(x) := \{k : g_k(x) = 0\}.$$

Then the constraint K is qualified at $x \in K$.

Proposition 5. *Let $g_i(x)$ be a C^1 convex function, and $h_j(x) = A_j^T x + b_j$. Assume that*

1. *$\{A_1, \dots, A_\ell\}$ is linearly independent.*
2. *There exists $\hat{x} \in \mathbb{R}^n$ such that*

$$\begin{aligned} g_i(\hat{x}) &< 0, \quad i = 1, \dots, m \\ h_j(\hat{x}) &= 0, \quad j = 1, \dots, \ell \end{aligned}$$

Then, qualification condition holds for all $x \in K$.

Proof. 1. To apply the Mangasarian Fromovitz condition, we check that

$$\{\nabla h_1(x), \dots, \nabla h_\ell(x)\} = \{A_1, \dots, A_\ell\}$$

is linearly independent.

2. For all $x \neq \hat{x}$, and satisfying $g_i(x) \leq 0, h_j(x) = 0$ and $g_i(\hat{x}) < 0, h_j(\hat{x}) = 0$. Put $v := \hat{x} - x$, then

$$0 = h_j(x) - h_j(\hat{x}) = A_j^T(\hat{x} - x) = \langle \nabla h_j(x), v \rangle$$

Further, when $g_i(x) = 0$, we have

$$\langle \nabla g_i(x), v \rangle = \langle \nabla g_i(x), \hat{x} - x \rangle \leq g_i(\hat{x}) - g_i(x) = g_i(\hat{x}) < 0$$

Thus, applying the Mangasarian Fromovitz condition, the proof is finished. □

— End of Lecture 17 —